## Page 1 of 3

## Exercise 10.1.5

Construct the Green's function for

$$x^{2}\frac{d^{2}y}{dx^{2}} + x\frac{dy}{dx} + (k^{2}x^{2} - 1)y = 0,$$

subject to the boundary conditions y(0) = 0, y(1) = 0.

## Solution

The Green's function for an operator  $\mathcal{L}$  satisfies

$$\mathcal{L}G = \delta(x-t).$$

## Part (a)

For the operator  $\mathcal{L} = x^2(d^2/dx^2) + x(d/dx) + k^2x^2 - 1$ , this equation becomes

$$x^{2}\frac{d^{2}G}{dx^{2}} + x\frac{dG}{dx} + (k^{2}x^{2} - 1)G = \delta(x - t).$$
(1)

If  $x \neq t$ , then the right side is zero.

$$x^{2}\frac{d^{2}G}{dx^{2}} + x\frac{dG}{dx} + (k^{2}x^{2} - 1)G = 0, \quad x \neq t$$

The general solution can be written in terms of first-order Bessel functions of the first and second kind. Different constants are needed for x < t and for x > t.

$$G(x,t) = \begin{cases} C_1 J_1(kx) + C_2 Y_1(kx) & \text{if } 0 \le x < t \\ C_3 J_1(kx) + C_4 Y_1(kx) & \text{if } t < x \le 1 \end{cases}$$

Four conditions are needed to determine these four constants. Two of them are obtained from the provided boundary conditions.

$$G(0,t) = 0 \qquad \Rightarrow \qquad C_2 = 0$$
  
 $G(1,t) = C_3 J_1(k) + C_4 Y_1(k) = 0 \qquad \rightarrow \qquad C_4 = -C_3 \frac{J_1(k)}{Y_1(k)}$ 

As a result, the Green's function becomes

$$G(x,t) = \begin{cases} C_1 J_1(kx) & \text{if } 0 \le x < t \\ C_3 J_1(kx) - C_3 \frac{J_1(k)}{Y_1(k)} Y_1(kx) & \text{if } t < x \le 1 \end{cases}.$$

The third condition comes from the fact that the Green's function must be continuous at x = t: G(t-,t) = G(t+,t).

$$C_1 J_1(kt) = C_3 J_1(kt) - C_3 \frac{J_1(k)}{Y_1(k)} Y_1(kt)$$
$$= C_3 \frac{J_1(kt)Y_1(k) - J_1(k)Y_1(kt)}{Y_1(k)}$$

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Solve for  $C_1$ .

$$C_1 = C_3 \frac{J_1(kt)Y_1(k) - J_1(k)Y_1(kt)}{J_1(kt)Y_1(k)}$$
(2)

The fourth and final condition is obtained from the defining equation of the Green's function, equation (1).

$$x^{2}\frac{d^{2}G}{dx^{2}} + x\frac{dG}{dx} + (k^{2}x^{2} - 1)G = \delta(x - t)$$

Integrate both sides with respect to x from t- to t+.

$$\begin{split} \int_{t_{-}}^{t_{+}} \left[ x^2 \frac{d^2 G}{dx^2} + x \frac{dG}{dx} + (k^2 x^2 - 1)G \right] dx &= \int_{t_{-}}^{t_{+}} \delta(x - t) \, dx \\ \int_{t_{-}}^{t_{+}} x^2 \frac{d^2 G}{dx^2} \, dx + \int_{t_{-}}^{t_{+}} x \frac{dG}{dx} \, dx + \underbrace{\int_{t_{-}}^{t_{+}} (k^2 x^2 - 1)G \, dx}_{= 0} = \underbrace{\int_{t_{-}}^{t_{+}} \delta(x - t) \, dx}_{= 1} \\ x^2 \frac{dG}{dx} \Big|_{t_{-}}^{t_{+}} - \int_{t_{-}}^{t_{+}} (2x) \frac{dG}{dx} \, dx + \int_{t_{-}}^{t_{+}} x \frac{dG}{dx} \, dx = 1 \\ x^2 \frac{dG}{dx} \Big|_{t_{-}}^{t_{+}} - \int_{t_{-}}^{t_{+}} x \frac{dG}{dx} \, dx = 1 \\ x^2 \frac{dG}{dx} \Big|_{t_{-}}^{t_{+}} - xG(x, t) \Big|_{t_{-}}^{t_{+}} + \int_{t_{-}}^{t_{+}} (1)G(x, t) \, dx = 1 \\ x^2 \frac{dG}{dx} \Big|_{t_{-}}^{t_{+}} - t[\underbrace{G(t_{+}, t) - G(t_{-}, t)}_{= 0}] + \underbrace{\int_{t_{-}}^{t_{+}} G(x, t) \, dx}_{= 0} = 1 \\ t^2 \left[ \frac{dG}{dx} (t_{+}, t) - \frac{dG}{dx} (t_{-}, t) \right] = 1 \end{split}$$

Divide both sides by  $t^2$ .

$$\begin{aligned} \frac{dG}{dx}(t+,t) - \frac{dG}{dx}(t-,t) &= \frac{1}{t^2} \\ \frac{d}{dx} \left[ C_3 J_1(kx) - C_3 \frac{J_1(k)}{Y_1(k)} Y_1(kx) \right] \Big|_{x=t} - \frac{d}{dx} \left[ C_1 J_1(kx) \right] \Big|_{x=t} &= \frac{1}{t^2} \\ C_3 \frac{k}{2} \frac{Y_1(k) [J_0(kt) - J_2(kt)] - J_1(k) [Y_0(kt) - Y_2(kt)]}{Y_1(k)} - C_1 \frac{k}{2} [J_0(kt) - J_2(kt)] &= \frac{1}{t^2} \end{aligned}$$

Multiply both sides by 2/k and substitute equation (2) for  $C_1$ .

$$C_{3}\frac{Y_{1}(k)[J_{0}(kt) - J_{2}(kt)] - J_{1}(k)[Y_{0}(kt) - Y_{2}(kt)]}{Y_{1}(k)} - C_{3}\frac{J_{1}(kt)Y_{1}(k) - J_{1}(k)Y_{1}(kt)}{J_{1}(kt)Y_{1}(k)}[J_{0}(kt) - J_{2}(kt)] = \frac{2}{kt^{2}}$$

$$C_{3} \frac{J_{0}(kt)J_{1}(k)Y_{1}(kt) - J_{1}(k)J_{1}(kt)Y_{0}(kt) - J_{1}(k)J_{2}(kt)Y_{1}(kt) + J_{1}(k)J_{1}(kt)Y_{2}(kt)}{J_{1}(kt)Y_{1}(k)} = \frac{2}{kt^{2}}$$

$$C_{3}J_{1}(k)\frac{Y_{1}(kt)[J_{0}(kt) - J_{2}(kt)] - J_{1}(kt)[Y_{0}(kt) - Y_{2}(kt)]}{J_{1}(kt)Y_{1}(k)} = \frac{2}{kt^{2}}$$

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Solve for  $C_3$ .

$$C_3 = \frac{2}{kt^2} \frac{1}{J_1(k)} \frac{J_1(kt)Y_1(k)}{Y_1(kt)[J_0(kt) - J_2(kt)] - J_1(kt)[Y_0(kt) - Y_2(kt)]}$$

Use equation (2) to get  $C_1$ .

$$\begin{split} C_1 &= C_3 \frac{J_1(kt)Y_1(k) - J_1(k)Y_1(kt)}{J_1(kt)Y_1(k)} \\ &= \frac{2}{kt^2} \frac{1}{J_1(k)} \frac{J_1(kt)Y_1(k) - J_1(k)Y_1(kt)}{Y_1(kt)[J_0(kt) - J_2(kt)] - J_1(kt)[Y_0(kt) - Y_2(kt)]} \end{split}$$

The Green's function for  $\mathcal{L} = x^2(d^2/dx^2) + x(d/dx) + k^2x^2 - 1$  subject to the provided boundary conditions is then

$$G(x,t) = \begin{cases} \frac{2}{kt^2} \frac{J_1(kx)}{J_1(k)} \frac{J_1(kt)Y_1(k) - J_1(k)Y_1(kt)}{Y_1(kt)[J_0(kt) - J_2(kt)] - J_1(kt)[Y_0(kt) - Y_2(kt)]} & \text{if } 0 \le x < t \\ \\ \frac{2}{kt^2} \frac{J_1(kt)}{J_1(k)} \frac{J_1(kx)Y_1(k) - J_1(k)Y_1(kx)}{Y_1(kt)[J_0(kt) - J_2(kt)] - J_1(kt)[Y_0(kt) - Y_2(kt)]} & \text{if } t < x \le 1 \end{cases}$$

This formula can be simplified by using the identity,

$$Y_1(kt)[J_0(kt) - J_2(kt)] - J_1(kt)[Y_0(kt) - Y_2(kt)] = -\frac{4}{\pi kt}.$$

Therefore,

$$G(x,t) = \begin{cases} \frac{\pi}{2t} \frac{J_1(kx)}{J_1(k)} \left[ J_1(k) Y_1(kt) - J_1(kt) Y_1(k) \right] & \text{if } 0 \le x < t \\ \\ \frac{\pi}{2t} \frac{J_1(kt)}{J_1(k)} \left[ J_1(k) Y_1(kx) - J_1(kx) Y_1(k) \right] & \text{if } t < x \le 1 \end{cases}$$